

Engineering & Robotics II | Course Overview

Year-Long Course Outline with CTE Competencies

Pre-requisites – Intro to Engineering and Robotics

Equipment Requirements – *FIRST* Tech Challenge Robotics Kit, *FIRST* Robotics Competition Robot, Design and Fabrication Equipment (3D Printers, CNC, or other Metal Fabrication)

Course Description

Engineering & Robotics II is an advanced, project-based course that builds on engineering design, robotics, programming, and documentation foundations established in Engineering & Robotics I. Students engage in deeper engineering challenges that require integration of mechanical design, advanced electronics, automation, sensors, control theory, and software development.

Learners apply industry-relevant engineering practices, including systems engineering, advanced CAD modeling, rapid prototyping, and data-driven optimization. The course culminates in a semester-long team engineering project or competition-style challenge using *FIRST* platforms such as *FIRST* Tech Challenge or *FIRST* Robotics Competition. This course prepares students for advanced CTE pathways in Engineering, Manufacturing, Information Technology, and Mechatronics.

Course Outcomes

| COMPETENCY | STUDENT OUTCOMES |
|---|---|
| Apply Advanced Engineering Design and Systems Engineering Processes | Students will use advanced problem-solving strategies to evaluate multiple solution pathways and apply systems-engineering methods when designing integrated robotic systems, while managing project requirements, constraints, risks, and trade-offs inherent in complex engineering challenges. |
| Develop and Optimize Advanced Mechanical Systems | Students will design and model multi-component mechanisms in CAD, apply force and torque calculations to guide design choices, prototype, test, and refine mechanisms through iterative engineering. |
| Implement Advanced Programming for Robotics Control Systems | Students will develop modular robot code, integrate advanced controls such as PID, state machines, and sensor fusion, and use communication protocols like CAN, serial, I2C, and wireless telemetry to create reliable robotic systems. |
| Integrate Sensors, Automation, and Electronics into Functional Systems | Students will build and troubleshoot complex electrical systems, apply principles like Ohm's law and circuit protection, and integrate microcontrollers to automate sensing, movement, and decision-making. |
| Use Data Acquisition and Analysis to Drive Engineering Optimization | Students will collect and interpret performance data to refine mechanical, electrical, and control systems, using statistical tools and spreadsheets to support evidence-based design decisions. |
| Advanced Project Management & Engineering Documentation | Students will manage projects using engineering notebooks, design reviews, revision tracking, and documentation tools, producing clear technical artifacts that support effective collaboration. |
| Team Leadership in Engineering Projects | Students will lead engineering teams by coordinating tasks, mentoring peers, resolving conflicts, and clearly communicating progress and decisions throughout complex projects. |
| Capstone Engineering Project | Students will design, build, test, and refine a fully integrated robotic or automated system, documenting their work and presenting evidence-based engineering decisions in a final demonstration. |

Industry Certifications

- Certified Onshape Associate or Fusion 360 Associate
- OSHA 10 Hour Safety Training

[FIRST Training](#) learning content that can be used to implement this course.

| Engineering Explorations Course | FIRST Robotics Competition Trainings | | UL Safety Trainings | |
|---------------------------------------|--|--------------------------------------|--------------------------------|---|
| Unit 1: Welcome to FIRST | Module 1: Intro to FIRST Robotics Competition | Module 7: Kickoff | Robotics Safety | Personal Protective Equipment |
| Unit 2: Build a Bot | Module 2: How does FIRST Robotics Competitions Work? | Module 8: Design and Mechanical | Giving and Receiving Feedback | Lockout/Tagout/Tryout |
| Unit 3: Make it Move | Module 3: Intro to CAD and 3D Printing | Module 9: Programming & Electrical | Cybersecurity | Hazard Communication-Safety Data Sheets |
| Unit 4: Programming Autonomous Robots | Module 4: Fabrication Tools and Safety | Module 10: Business and Media | Recognizing Electrical Hazards | Hand and Power Tool Safety |
| Unit 5: Build & Program Manipulators | Module 5: Rapid Prototyping | Module 11: Preparing for Competition | Fire Extinguisher Safety | |
| Unit 6: The Ball Game | Module 6: Preparing for Build Season | Module 12: Season Wrap-up | | |
| | Java Programming I | Java Programming II | | |

Standards Alignment

| Organization | Aligned Standards |
|--------------|--|
| NGSS | HS-ETS1-1, HS-ETS1-2, HS-ETS1-3, HS-ETS1-4, HS-PS2-1, HS-PS2-2, HS-PS3-1, HS-PS3-3, HS-PS4-5 |
| ISTE | 1.1.a, 1.1.c, 1.2.a, 1.2.b, 1.4.a, 1.4.b, 1.5.a, 1.5.b, 1.5.c, 1.6.a, 1.6.b, 1.7.a, 1.7.b |
| ITEEA (STEL) | 1M, 2P, 3J, 4I, 5H, 6F, 7J, 8J, 9K, 10L |
| NIMS | Measurement Materials & Safety (MMS), Job Planning Benchwork & Layout, Quality & Continuous Improvement, Industrial Technology Maintenance Awareness, CNC Operations (Intro), Electrical Systems (Fundamentals), Workforce Readiness |
| NBEA | Information Technology II.A, Information Technology III.A, Communication III.A, Management III.A, Career Development I.B |
| ACTE-CRP | CRP1, CRP2, CRP4, CRP5, CRP6, CRP7, CRP8, CRP9, CRP10, CRP11, CRP12 |